

$$\hat{\pi}_t = \frac{\theta[1-(1-\theta)\beta]}{1-\theta} \hat{m}_{t|t}^r + \beta E_t \hat{\pi}_{t+1}$$

通货膨胀方程

- ① 季→粘 法1
 - ② 季→粘 法2
- NK PC 线 & Dynamic IS 曲线

厂商最小化成本 (短中期)

$$\min \frac{w_t}{p_t} N_t$$

$$s.t. A_t N_t^{1-\alpha} = Y_t$$

$$\mathcal{L} = \frac{w_t}{p_t} N_t + \underbrace{MC_t^r}_{MC_t^r} (Y_t - A_t N_t^{1-\alpha})$$

FOC: $\frac{\partial \mathcal{L}}{\partial N_t} = 0$

$$\Rightarrow \frac{w_t}{p_t} = MC_t^r (1-\alpha) A_t N_t^{-\alpha}$$

$$\Rightarrow MC_t^r = \frac{w_t/p_t}{MPN_t}$$

劳动边际产出

对数线性化

$$\hat{m}_{t|t}^r = \hat{w}_t - \hat{p}_t - (\alpha_t - \alpha \hat{n}_t)$$

$$= \sigma \hat{y}_t + \varphi \hat{n}_t - (\alpha_t - \alpha \hat{n}_t)$$

$$= \sigma \hat{y}_t - \alpha_t + (\varphi + \alpha) \hat{n}_t$$

$$= \sigma \hat{y}_t - \alpha_t + (\varphi + \alpha) \frac{\hat{y}_t - \alpha_t}{1-\alpha}$$

$$= \frac{\sigma(1-\alpha) + (\varphi + \alpha)}{1-\alpha} \hat{y}_t - \frac{1+\varphi}{1-\alpha} \alpha_t$$

家庭部门最优 FOC: 劳动供给方程

$$\frac{w_t}{p_t} = C_t^\sigma N_t^\varphi = Y_t^\sigma N_t^\varphi$$

$$Y_t = A_t N_t^{1-\alpha}$$

def $\tilde{y}_t = \hat{y}_t - \hat{y}_t^f$ (产出缺口)

稳态时对应的产出 \hat{y}_t^f

$$0 = \hat{m}_{t|t}^r = \frac{\sigma(1-\alpha) + (\varphi + \alpha)}{1-\alpha} \hat{y}_t^f - \frac{1+\varphi}{1-\alpha} \alpha_t$$

$$\Rightarrow \frac{1+\varphi}{1-\alpha} \alpha_t = \frac{\sigma(1-\alpha) + (\varphi + \alpha)}{1-\alpha} \hat{y}_t^f$$

$$\hat{m}_{t|t}^r = \frac{\sigma(1-\alpha) + (\varphi + \alpha)}{1-\alpha} \tilde{y}_t$$

$$\hat{\pi}_t = \beta E_t \hat{\pi}_{t+1} + \chi \tilde{y}_t, \quad \chi = \frac{\theta[1-(1-\theta)\beta]}{1-\theta} \cdot \frac{\sigma(1-\alpha) + (\varphi + \alpha)}{1-\alpha}$$

NKPC

$\tilde{y}_t \uparrow$: 经济景气 $\Rightarrow \hat{\pi}_t \uparrow$

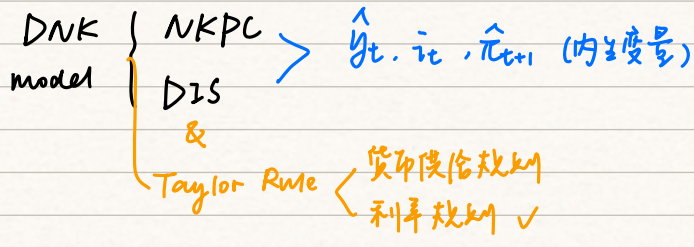
Dynamic IS

$$\hat{c}_t = E_t \hat{c}_{t+1} - \frac{1}{\sigma} (i_t - E_t \hat{\pi}_{t+1})$$

均衡 $\Rightarrow \hat{y}_t = E_t \hat{y}_{t+1} - \frac{1}{\sigma} (i_t - E_t \hat{\pi}_{t+1})$

def $\hat{y}_t^f = E_t \hat{y}_{t+1}^f - \frac{1}{\sigma} (i_t^f - 0)$

$$\tilde{y}_t = \hat{y}_t - \hat{y}_t^f = E_t \tilde{y}_{t+1} - \frac{1}{\sigma} (i_t - i_t^f - E_t \hat{\pi}_{t+1})$$



$$\begin{cases} \hat{\pi}_t = \beta E_t \hat{\pi}_{t+1} + \chi \tilde{y}_t \\ \tilde{y}_t = E_t \tilde{y}_{t+1} - \frac{1}{\sigma} (i_t - i_t^f - E_t \hat{\pi}_{t+1}) \\ m_t = \hat{p}_t + \hat{y}_t - \eta \hat{i}_t \quad (MZC \text{ 货币进入效用函数的 FOC}) \end{cases}$$

$\Delta m_t = \rho_m \Delta m_{t-1} + \varepsilon_t^m$

法二. 推导 NKPC

1. 先写利润表

$$\max_{P_t} \pi_{it}^r = (1-\tau_c) \left(\frac{P_t}{P_t}\right) Y_{it} - \frac{w_t}{P_t} N_{it}$$

s.t. $Y_{it} = A_t N_{it}^{1-\alpha}$, $\alpha=0$

$$Y_{it} = \left(\frac{P_t}{P_t}\right)^{-\varepsilon} Y_t$$

$$\begin{aligned} \pi_{it}^r &= (1-\tau_c) \frac{P_t}{P_t} \left(\frac{P_t}{P_t}\right)^{-\varepsilon} Y_t - \frac{w_t}{P_t} \cdot \left(\frac{P_t}{P_t}\right)^{-\varepsilon} \frac{Y_t}{A_t} \\ &= (1-\tau_c) \left(\frac{P_t}{P_t}\right)^{1-\varepsilon} Y_t - \frac{w_t}{P_t} \cdot \left(\frac{P_t}{P_t}\right)^{-\varepsilon} \frac{Y_t}{A_t} \end{aligned}$$

FOC: $\frac{\partial \pi_{it}^r}{\partial P_t} = 0 \Rightarrow \frac{P_t^*}{P_t} = \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_c} \cdot \frac{w_t/P_t}{A_t}$

$\Rightarrow \frac{P_t^*}{P_t} = \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_c} \cdot \frac{Y_t^\sigma N_t^\varphi}{A_t}$

$$\begin{aligned}
&= \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^\sigma}{A_t} \cdot \left(\int_0^1 N_{it} di \right)^\varphi \\
&= B \left(\int_0^1 \frac{Y_{it}}{A_t} di \right)^\varphi \\
&= \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^\sigma}{A_t^{1+\varphi}} \left(\int_0^1 Y_{it} di \right)^\varphi \\
&= \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^\sigma}{A_t^{1+\varphi}} \left[\int_0^1 \left(\frac{P_{it}^*}{P_t} \right)^{-\varepsilon} Y_{it} di \right]^\varphi \\
&= \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^{\sigma+\varphi}}{A_t^{1+\varphi}} \left[\int_0^1 \left(\frac{P_{it}^*}{P_t} \right)^{-\varepsilon} di \right]^\varphi \\
&= \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^{\sigma+\varphi}}{A_t^{1+\varphi}} \left(\frac{P_t^*}{P_t} \right)^{-\varepsilon \varphi}
\end{aligned}$$

价格弹性为 $\frac{P_{it}^*}{P_t} = \frac{P_t^*}{P_t} = 1$

$$1 = \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^{\sigma+\varphi}}{A_t^{1+\varphi}} \Rightarrow Y_t^f = ?$$

$$\left(\frac{P_{it}^*}{P_t} \right)^{1+\varepsilon\varphi} = \frac{\varepsilon}{\varepsilon-1} \cdot \frac{1}{1-\tau_t} \cdot \frac{Y_t^{\sigma+\varphi}}{A_t^{1+\varphi}}$$

对数线性化

取对数 $(1+\varepsilon\varphi)(p_t^* - p_t) = \ln \frac{\varepsilon}{\varepsilon-1} + \ln \frac{1}{1-\tau_t} + (\sigma+\varphi) y_t - (1+\varphi) a_t$

$$\Rightarrow p_t^* = p_t + \frac{\sigma+\varphi}{1+\varepsilon\varphi} y_t - \frac{1+\varphi}{1+\varepsilon\varphi} a_t + \frac{1}{1+\varepsilon\varphi} \ln \frac{\varepsilon}{\varepsilon-1} - \frac{1}{1+\varepsilon\varphi} \ln(1-\tau_t)$$

减去稳态

$$\begin{aligned}
\hat{p}_t^* &= p_t^* - p^* \\
&= \hat{p}_t + \frac{\sigma+\varphi}{1+\varepsilon\varphi} \hat{y}_t - \frac{1+\varphi}{1+\varepsilon\varphi} \hat{a}_t - \frac{1}{1+\varepsilon\varphi} [\ln(1-\tau_t) - \ln(1-\tau)]
\end{aligned}$$

$$= C - \frac{1}{1+\varepsilon\varphi} \left[\cancel{\ln(1-\tau)} - \frac{\tau}{1-\tau} (\tau_t - \tau) - \cancel{\ln(1-\tau)} \right]$$

$$= \hat{p}_t + \frac{\sigma+\varphi}{1+\varepsilon\varphi} \hat{y}_t - \frac{1+\varphi}{1+\varepsilon\varphi} \hat{a}_t - \frac{\tau}{(1+\varepsilon\varphi)(1-\tau)} \hat{\tau}_t$$

$$0 = \frac{\sigma+\varphi}{1+\varepsilon\varphi} \hat{y}_t^f - \frac{1+\varphi}{1+\varepsilon\varphi} \hat{a}_t - \frac{\tau}{(1+\varepsilon\varphi)(1-\tau)} \hat{\tau}_t$$

$$\Rightarrow \hat{y}_t^f = \frac{1}{\sigma+\varphi} \left[(1+\varphi) \hat{a}_t + \frac{\tau}{1-\tau} \hat{\tau}_t \right]$$

$$\Rightarrow \hat{p}_t^* = \hat{p}_t + \gamma (\hat{y}_t - \hat{y}_t^f), \quad \gamma = \frac{\sigma+\varphi}{1+\varepsilon\varphi} \quad \text{desired price}$$

2. 价格粘性 - prob = 0

$$\hat{p}_t^0 = (1-\theta\beta) \sum_{k=0}^{\infty} (\theta\beta)^k E_t \hat{p}_{t+k}^*$$

调整价格

$$= (1-\theta\beta) \hat{p}_t^* + (1-\theta\beta) \theta\beta E_t \hat{p}_{t+1}^* + (1-\theta\beta)(\theta\beta)^2 E_t \hat{p}_{t+2}^* + \dots$$

$$\hat{p}_t = (1-\theta) \sum_{k=0}^{\infty} \theta^k \hat{p}_{t-k}^{\Delta} = (1-\theta) \hat{p}_t^{\Delta} + \theta \hat{p}_{t-1}$$

$$\hat{p}_t^* = \hat{p}_t + \gamma (\hat{y}_t - \hat{y}_t^f), \quad \gamma = \frac{\sigma + \varphi}{1 + \varepsilon \varphi} \quad \text{desired price}$$

$$\hat{p}_t^0 = (1-\theta\beta) \sum_{k=0}^{\infty} (\theta\beta)^k E_t \hat{p}_{t+k}^* \quad \text{调整价格方程}$$

$$\hat{p}_t = (1-\theta) \sum_{k=0}^{\infty} \theta^k \hat{p}_{t-k}^{\Delta} = (1-\theta) \hat{p}_t^{\Delta} + \theta \hat{p}_{t-1}$$

法 = 推导 NKPL

$$\hat{p}_t = (1-\theta) \hat{p}_t^{\Delta} + \theta \hat{p}_{t-1}$$

$$(1-\theta) \hat{p}_t^{\Delta} = \hat{p}_t - \theta \hat{p}_{t-1}$$

向前一期

$$(1-\theta) E_t \hat{p}_{t+1}^{\Delta} = E_t \hat{p}_{t+1} - \theta \hat{p}_t$$

$$\hat{p}_t^{\Delta} = (1-\theta\beta) \hat{p}_t^* + \theta\beta E_t \hat{p}_{t+1}^{\Delta}$$

$$(1-\theta) \hat{p}_t^{\Delta} = (1-\theta)(1-\theta\beta) \hat{p}_t^* + (1-\theta)\theta\beta E_t \hat{p}_{t+1}^{\Delta}$$

$$(1-\theta) \hat{p}_t^{\Delta} = (1-\theta)(1-\theta\beta) [\hat{p}_t + \gamma (\hat{y}_t - \hat{y}_t^f)] + (1-\theta)\theta\beta E_t \hat{p}_{t+1}^{\Delta}$$

$$\hat{p}_t - \theta \hat{p}_{t-1} = (1-\theta)(1-\theta\beta) [\hat{p}_t + \gamma (\hat{y}_t - \hat{y}_t^f)] + \theta\beta E_t \hat{p}_{t+1} - \theta\beta \hat{p}_t$$

合并同类项

$$[1 + \theta\beta - (1-\theta)(1-\theta\beta)] \hat{p}_t - \theta \hat{p}_{t-1} = (1-\theta)(1-\theta\beta) [\hat{p}_t + \gamma (\hat{y}_t - \hat{y}_t^f)] + \theta\beta E_t \hat{p}_{t+1}$$

$(\theta\beta + \theta) \hat{p}_t$

$$(\theta\beta + \theta) \hat{p}_t - \theta \hat{p}_{t-1} - \theta\beta \hat{p}_t = (1-\theta)(1-\theta\beta) [\gamma (\hat{y}_t - \hat{y}_t^f)] + \theta\beta (E_t \hat{p}_{t+1} - \hat{p}_t)$$

$$\theta (\hat{p}_t - \hat{p}_{t-1}) = (1-\theta)(1-\theta\beta) [\gamma (\hat{y}_t - \hat{y}_t^f)] + \theta\beta (E_t \hat{p}_{t+1} - \hat{p}_t)$$

$$\theta \hat{\pi}_t = (1-\theta)(1-\theta\beta) [\gamma (\hat{y}_t - \hat{y}_t^f)] + \theta\beta E_t \hat{\pi}_{t+1}$$

$$\hat{\pi}_t = \frac{(1-\theta)(1-\theta\beta)}{\theta} [\gamma (\hat{y}_t - \hat{y}_t^f)] + \beta E_t \hat{\pi}_{t+1}$$

$$\hat{\pi}_t = \alpha \tilde{y}_t + \beta E_t \hat{\pi}_{t+1}$$

ZS + 实际货币余额方程 $\Rightarrow m_t = \hat{p}_t + \hat{y}_t$

$$\begin{cases} \hat{\pi}_t = \alpha \tilde{y}_t + \beta E_t \hat{\pi}_{t+1} \\ \text{设 } \hat{y}_t^f = 0 \end{cases}$$

$$\hat{p}_t - \hat{p}_{t-1} = \beta (m_t - \hat{p}_t) + E_t (\hat{p}_{t+1} - \hat{p}_t)$$

$$\Rightarrow E_t \hat{p}_{t+1} - (2+\beta) \hat{p}_t + \hat{p}_{t-1} = -\beta m_t$$

$$\Rightarrow [F^2 - (2+\beta)F + 1] L \hat{p}_t^e = -\beta m_t$$

$$\lambda_1 + \lambda_2 = 2+\beta \quad \lambda_1, \lambda_2 = 1 \quad \text{设 } \lambda_1 = 0, \lambda_2 = \frac{1}{\theta} \quad \Rightarrow \beta = \frac{(\theta-1)^2}{\theta} \quad F = L^{-1}$$

$$(1-\lambda_1 F)(1-\lambda_2 F) L \hat{p}_t^e = -\beta m_t$$

$$(1-\theta F)(1-\theta L) \hat{p}_t^e = (-\theta)(-\beta) m_t$$

$$(1-\theta L) \hat{p}_t^e = (1-\theta)^2 (1-\theta F)^{-1} m_t$$

$$\Rightarrow \hat{p}_t = \theta \hat{p}_{t-1} + (1-\theta)^2 \sum_{i=0}^{\infty} \theta^i E_t m_{t+i}$$

" (1+\theta F + \theta^2 F^2 + \dots) 几何级数"

利率规则

1) -MP - PL

$$\begin{cases} \hat{\pi}_t = \alpha \tilde{y}_t + \beta E_t \hat{\pi}_{t+1} \\ \text{设 } \hat{y}_t^f = 0 \\ \tilde{y}_t = E_t \tilde{y}_{t+1} - \frac{1}{\sigma} (\hat{v}_t - E_t \hat{\pi}_{t+1}) \\ \hat{v}_t = \phi_\pi \hat{\pi}_t + \phi_y \tilde{y}_t + v_t \quad \text{Taylor Rules} \quad v_t = \rho v_{t-1} + \varepsilon_t^v \end{cases}$$

B-K 条件

$$\hat{y}_t = E_t \hat{y}_{t+1} - \frac{1}{\sigma} [\phi_\pi \hat{\pi}_t + \phi_y \tilde{y}_t + v_t] - E_t \hat{\pi}_{t+1}$$

$$= E_t \hat{y}_{t+1} - \frac{1}{\sigma} \left\{ [\phi_\pi (\beta E_t \hat{\pi}_{t+1} + \alpha \tilde{y}_t) + \phi_y \tilde{y}_t + v_t] - E_t \hat{\pi}_{t+1} \right\}$$

$$= E_t \tilde{y}_{t+1} + \frac{1+\beta\phi_\pi}{\sigma} E_t \hat{\pi}_{t+1} - \frac{\phi_\pi \alpha + \phi_y}{\sigma} \tilde{y}_t - \frac{v_t}{\sigma}$$

$$\hat{y}_t = \frac{1}{\sigma + \phi_\pi \alpha + \phi_y} \left[\sigma E_t \tilde{y}_{t+1} + (1 - \beta \phi_\pi) E_t \hat{\pi}_{t+1} - v_t \right]$$

$$\hat{\pi}_t = \beta E_t \hat{\pi}_{t+1} + \alpha \tilde{y}_t$$

$$= \beta E_t \hat{\pi}_{t+1} + \frac{\alpha}{\sigma + \phi_\pi \alpha + \phi_y} \left[\sigma E_t \tilde{y}_{t+1} + (1 - \beta \phi_\pi) E_t \hat{\pi}_{t+1} - v_t \right]$$

$$= \frac{1}{\sigma + \phi_\pi \alpha + \phi_y} \left\{ \alpha \sigma E_t \tilde{y}_{t+1} + [\alpha + \beta(\sigma + \phi_y)] E_t \hat{\pi}_{t+1} - \alpha v_t \right\}$$

随机游走-PII
差分系统

$$\Rightarrow \begin{bmatrix} \tilde{y}_t \\ \hat{\pi}_t \end{bmatrix} = \frac{1}{\sigma + \phi_\pi \alpha + \phi_y} \begin{bmatrix} \sigma & 1 - \beta \phi_\pi \\ \alpha \sigma & \alpha + \beta(\sigma + \phi_y) \end{bmatrix} \begin{bmatrix} E_t \tilde{y}_{t+1} \\ E_t \hat{\pi}_{t+1} \end{bmatrix} - \frac{1}{\sigma + \phi_\pi \alpha + \phi_y} \begin{bmatrix} 1 \\ \alpha \end{bmatrix} v_t$$

$$\begin{bmatrix} \tilde{y}_t \\ \hat{\pi}_t \end{bmatrix} = A \begin{bmatrix} E_t \tilde{y}_{t+1} \\ E_t \hat{\pi}_{t+1} \end{bmatrix} - B v_t$$

待定系数法:

$$\begin{cases} \tilde{y}_t = \psi_{yv} v_t \\ \hat{\pi}_t = \psi_{\pi v} v_t \end{cases}$$

代入PII

$$\hat{\pi}_t = \beta E_t \hat{\pi}_{t+1} + \alpha \tilde{y}_t$$

$$\psi_{\pi v} v_t = \beta E_t \psi_{\pi v} v_{t+1} + \alpha \psi_{yv} v_t$$

$$= \beta E_t \psi_{\pi v} (\rho_v v_t + \varepsilon_{t+1}^v) + \alpha \psi_{yv} v_t$$

$$= \beta \psi_{\pi v} \rho_v v_t + \alpha \psi_{yv} v_t$$

$$\Rightarrow (1 - \beta \rho_v) \psi_{\pi v} v_t = \alpha \psi_{yv} v_t$$

$$\Rightarrow \psi_{yv} = \frac{1 - \beta \rho_v}{\alpha} \psi_{\pi v}$$

代入DII

$$\tilde{y}_t = E_t \tilde{y}_{t+1} - \frac{1}{\sigma} (\hat{v}_t - E_t \hat{\pi}_{t+1}) \quad \downarrow \text{PII } \hat{v}_t$$

$$= E_t \tilde{y}_{t+1} - \frac{1}{\sigma} \left[(\phi_\pi \hat{\pi}_t + \phi_y \tilde{y}_t + v_t) - E_t \hat{\pi}_{t+1} \right]$$

$$\psi_{yv} v_t = \psi_{yv} E_t (\rho_v v_t + \varepsilon_{t+1}^v) - \frac{1}{\sigma} \left[\phi_\pi \psi_{\pi v} v_t + \phi_y \psi_{yv} v_t + v_t - \phi_{\pi v} E_t (\rho_v v_t + \varepsilon_{t+1}^v) \right]$$

$$= \frac{\sigma \rho_v - \phi_y}{\sigma} \psi_{yv} v_t - \frac{\phi_\pi - \rho_v}{\sigma} \psi_{\pi v} v_t - \frac{1}{\sigma} v_t$$

$$\sigma \psi_{yv} = (\sigma \beta v - \phi_y) \psi_{yv} - (\phi_x - \beta v) \psi_{xv} - 1$$

$$[\sigma (1 - \beta v) + \phi_y] \psi_{yv} + (\phi_x - \beta v) \psi_{xv} = -1$$

$$\frac{1 - \beta v}{\alpha} \psi_{xv}$$

⇓

$$\psi_{xv} = \frac{-\alpha}{(1 - \beta v) [\sigma (1 - \beta v) + \phi_y] + \alpha (\phi_x - \beta v)} = -\alpha \lambda v, \lambda v > 0$$

$$\psi_{yv} = \frac{1 - \beta v}{\alpha} \psi_{xv} = (1 - \beta v) \lambda v.$$